Bryan Stiles and Brian Pollard California Institute of Technology Jet Propulsion Laboratory

of Technology, under a contract from the National Aeronautics and Space Administration. The research described in this poster was carried out by the Jet Propulsion Laboratory, California Institute



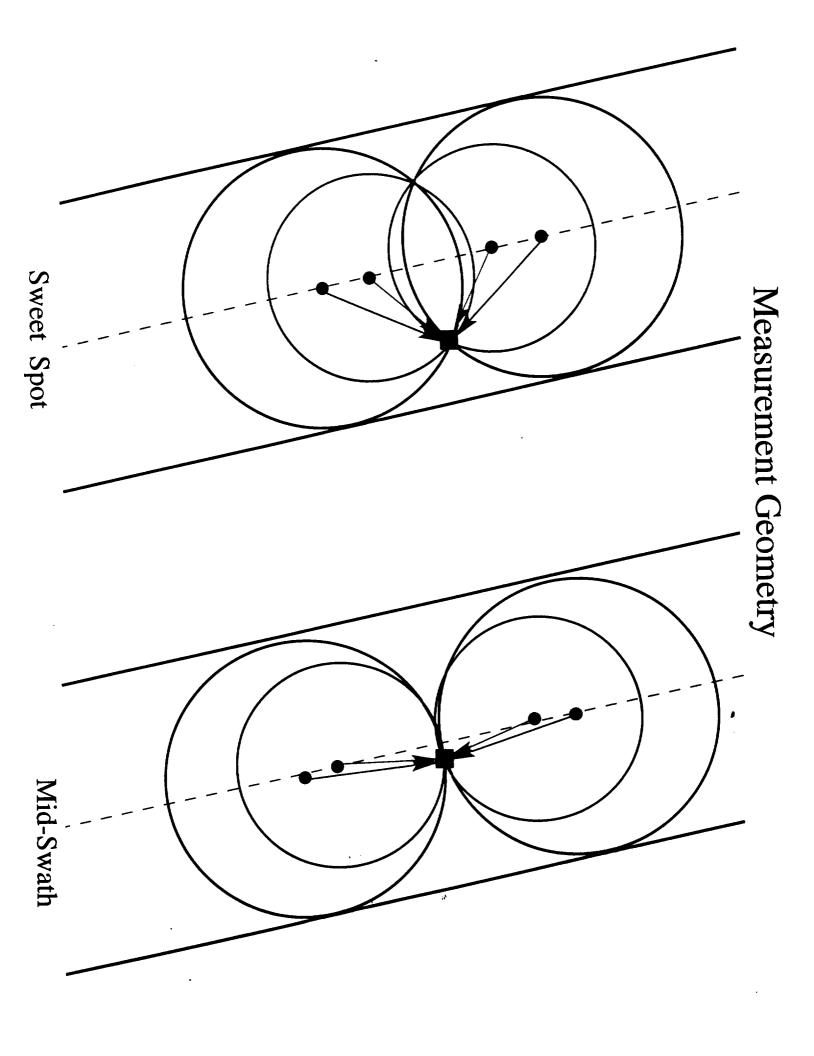
For more information

contact:

- Bryan Stiles
 4800 Oak Grove Dr.
 Mail Stop 300-319
 Pasadena, CA 91109
- Bryan.W.Stiles@jpl.
 nasa.gov

Abstract

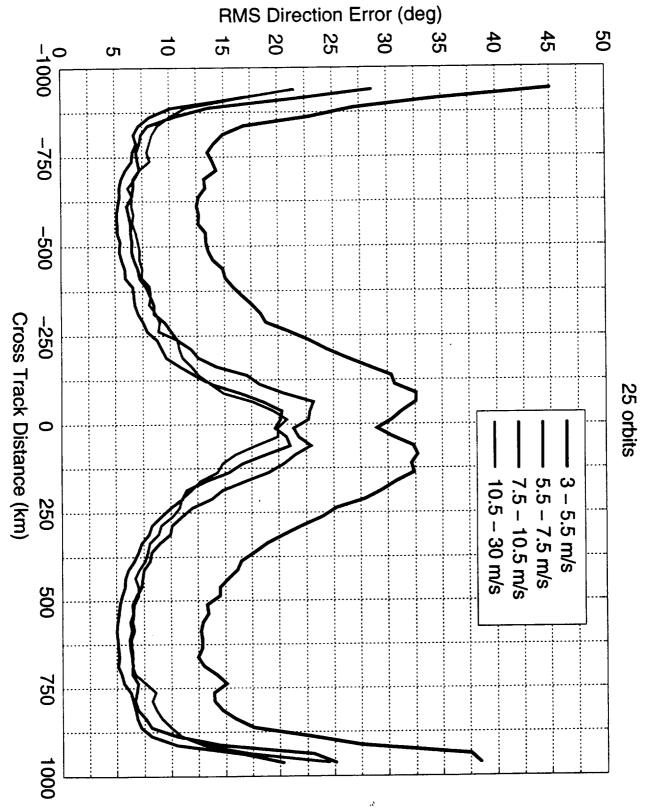
swath accuracy is worse than that of the rest of the swath. This behavior is a general the performance of the instrument prior to its launch have indicated that the midcharacteristic of scanning pencil beam scatterometers. For SeaWinds, the accuracy of the speed and direction of ocean surface winds. Simulations performed to estimate instrument varies with cross track distance, wind speed, and direction. By estimating problem at mid-swath, we can improve the performance there as well. We discuss the science requirements despite mid-swath shortcomings. However, by understanding the the rest of the swath, and the size of the swath are such that the instrument meets its direction errors without significantly degrading the resolution of the resultant wind field. information from neighboring cells where necessary in order to reduce random wind the range of likely wind directions for each measurement cell, one can optimally apply which improves mid-swath performance. The directional discrimination ability of the underlying causes of the problem in detail and propose a new wind retrieval algorithm time preserving high resolution structures such as cyclones and fronts In this manner we are able to achieve mid-swath RMS wind direction errors as low as 15 degrees for low winds and 10 degrees for moderate to high winds, while at the same The SeaWinds on QuikSCAT scatterometer was developed by NASA JPL to measure



Standard Wind Retrieval Algorithm

- pointwise wind retrieval
- maximum likelihood estimator
- multiple peaks in objective function
- ambiguity removal
- initialization using an external model ("nudge") wind field
- multi-pass median filtering

Baseline Nearest RMS Direction Error



<u>1</u>5 **Baseline Nearest RMS Speed Error** 25 orbits 3 - 5.5 m/s5.5 - 7.5 m/s7.5 – 10.5 m/s 10.5 - 30 m/s

2

RMS Speed Error (m/s)

0.5

0 -1000

-750

-500

-250

0

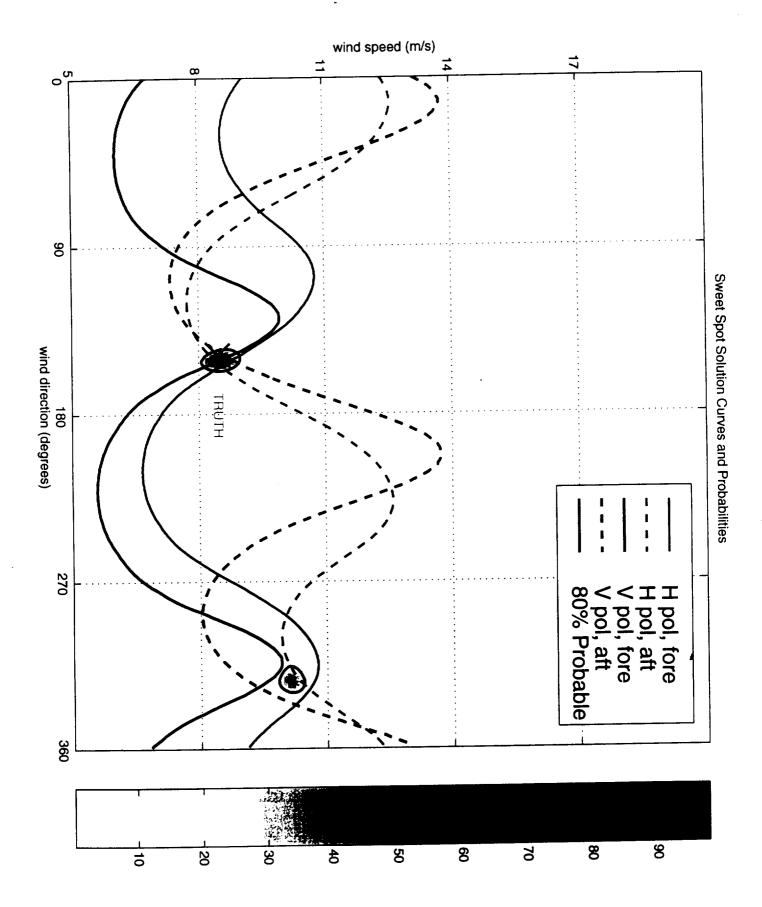
250

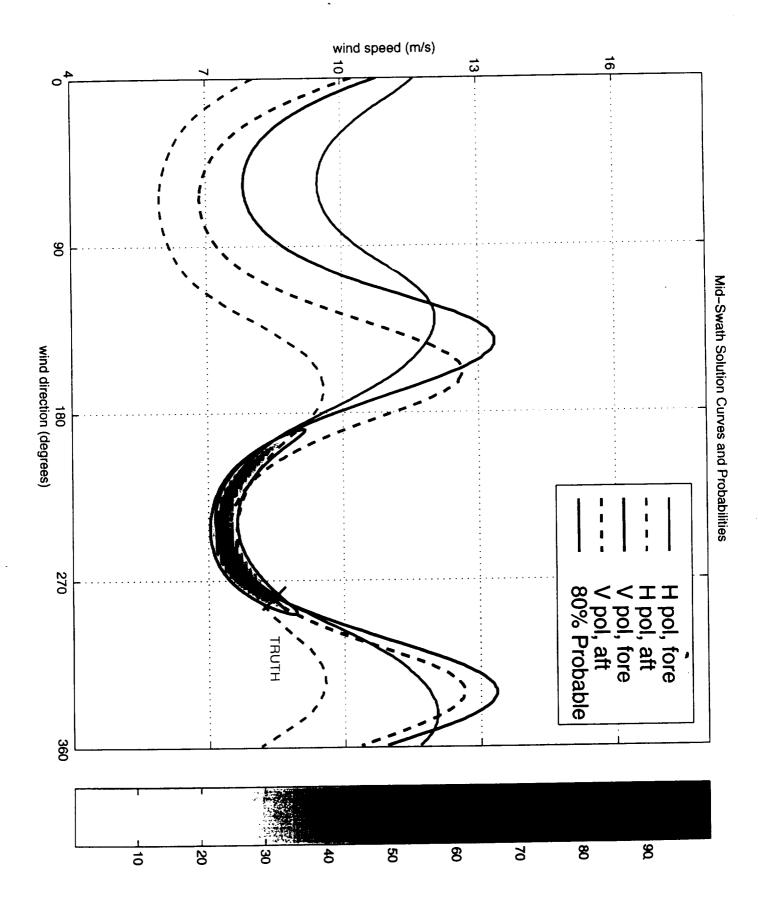
500

750

1000

Cross Track Distance (km)



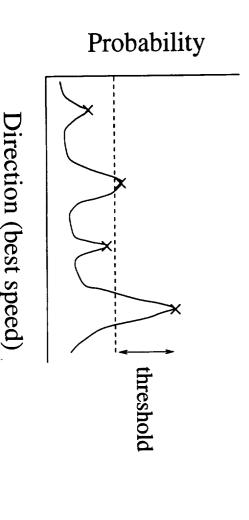


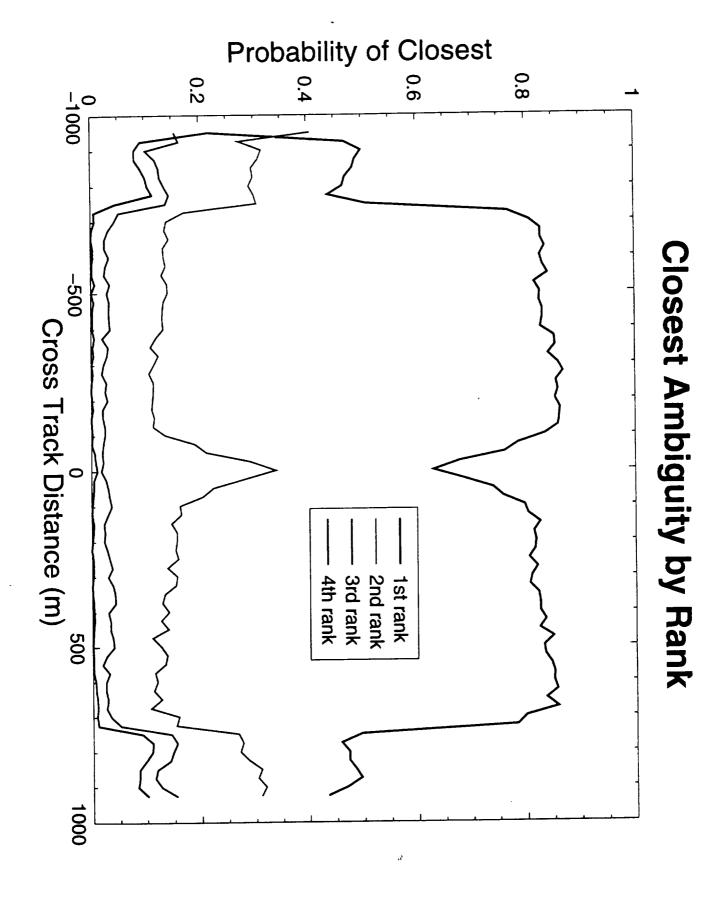
Mid-Swath Enhancement Technique

- pointwise wind retrieval
- estimate 80 percent error bounds on retrieved ambiguities
- ambiguity removal
- first stage: select best ambiguity
- second stage: select best direction within the error bounds for that ambiguity

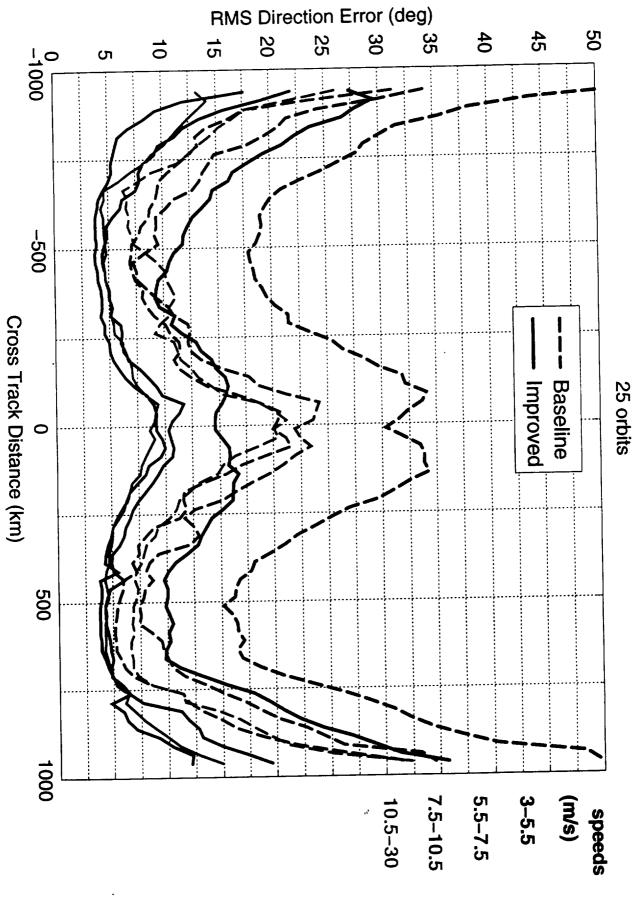
Far-Swath Enhancement Technique

- baseline wind retrieval:
- locate up to four ambiguities
- initialize the median filter with the closest of the top two ambiguities to the model field
- median filter
- thresholded wind retrieval:
- limit the number of ambiguities available for initialization based on a threshold value

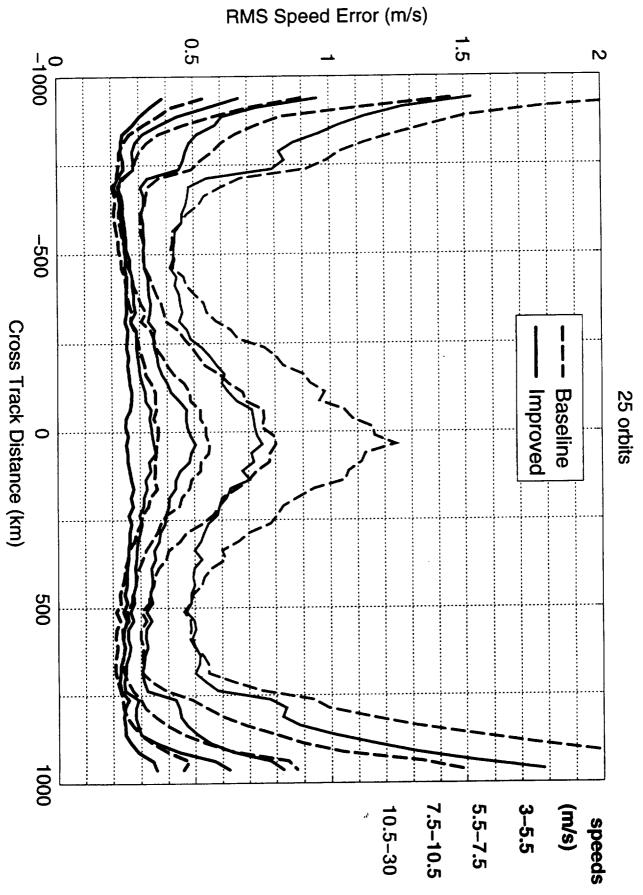




Comparison of Selected RMS Direction Error



Comparison of Selected RMS Speed Error



Wind field 1, Improved Wind field 2, Improved Example Wind Fields Wind field 2, Baseline Wind field 1, Baseline